

MHK515-LINK | SERIES

POWERLINK ABSOLUTE MULTI-TURN ENCODERS



MHK515-LINK, THE STANDARD Ø 58 MM ENCODER WITH POWERLINK TRANSMISSION

- · Compact and robust design
- Ø 15 mm hollow shaft version (reduction sleeve available)
- · Precision bearing with seal
- High performance in temperature range 0 °C to 60 °C
- Encoder disc made of durable unbreakable material
- Mechanical count of the number of revolutions per gear
- Resolution: 13-bit = 8,192 ppr (max. 16-bit)
- Number of revolutions: 12-bit = 4,096 revolutions
- Surge and reverse polarity protection
- Integrated SMC technology
- M12 connectors



MECHANICAL SPECIFICATIONS

Material (stainless steel option)	Cover: Aluminum	Shock resistance (EN 60068-2-27)	≤ 100 g (half sine, 6 ms)	
	Base: Aluminum	SHOCK resistance (LIV 00000-2-27)		
	Shaft: Stainless steel	Shock resistance (EN 60028-2-29)	≤ 10 g (half sine, 16 ms)	
Maximum loads	Axial: 40 N	Vibrations (EN 60068-2-6)	≤ 10 g (10 Hz1,000 Hz)	
	Radial: 110 N	Weight (aluminum version)	600 g	
Shaft inertia	. 20 a om²	Operating temperature	060 °C	
Silait illertia	≤ 30 g.cm²	Storage temperature	10 g (10 Hz1,000 Hz) 10 g60 °C 0+85 °C 3% non-condensing	
Torque	≤3 N.cm	Relative humidity	98% non-condensing	
Speed (max. continuous)	6,000 rpm	Degree of protection	Cover: IP65, Base: IP64	



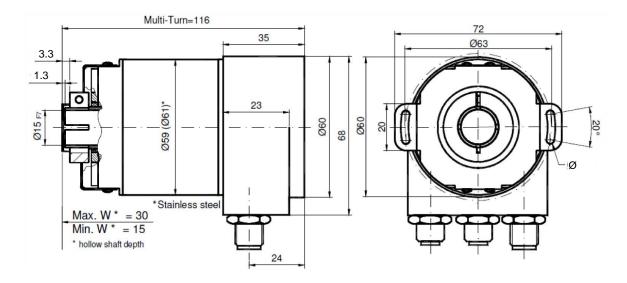
ELECTRICAL SPECIFICATIONS

Transmission	100 Mbps	Internal cycle time	500 μs
IP addressing	By rotary switches	Frequency on the LSB	800 kHz max. (valid code)
Power supply	10 – 30 VDC	Accuracy	+ ½ LSB
Consumption	100 mA max. (24 VDC)	EMC	EN 61000-6-4, EN 61000-6-2
Power	4 W max.	Electrical lifetime	> 10 ⁵ h

PROTOCOLS

TCP/UDP	The TCP protocol ensures error-free data transmission. The UDP protocol can be used for improved real-time transmission.
http	A web browser can be used for reading, configuring, and diagnosing the encoder.
smtp	Encoder messages can be transmitted by email via the SMTP protocol.

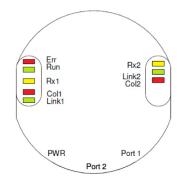






DIAGNOSIS VIA LEDS

LED	Color	Description of LED on
Rx1	Yellow	Inbound and outbound traffic – port 1
Link 1*	Green	Connected to another Ethernet component – port 1
Collision 1*	Red	Ethernet collision - port 1
Rx2+*	Yellow	Inbound and outbound traffic – port 2
Link 2*	Green	Connected to another Ethernet component – port 2
Collision 2*	Red	Ethernet collision - port 2
Error*	Red	-
Run*	Green	-



^{*} A1 versions only



PROGRAMMABLE SETTINGS

Direction of code change	Used to set whether the code increases with a clockwise turn and decreases with a counterclockwise turn, or vice versa.				
Resolution (number of positions per revolution)	The resolution parameter is used to program the desired number of steps per revolution. Any value between 1 and the physical resolution of the encoder (8,192 as standard) is programmable.				
Global resolution "Max-Range"	This is the total resolution required on the measurement scale. This value should not exceed the maximum encoder resolution (25-bit: 33.554.432).				
Reset to value X	The preset value represents the desired position value at any position on the axis. This parameter is used to set the desired value at the desired location.				



The node number is configured using 2 rotary switches (between 1 and 239).

Ethernet Powerlink

4-pin female, D-coded

Pin	Signal
1	Tx+
2	Rx+
3	Tx-
4	Rx-

Encoder view

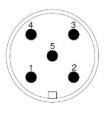


Power supply

5-pin male, A-coded

Signal
VS (10-30 VDC)
VS (10-30 VDC)
0 V
0 V
PE

Encoder view





(Special versions available on request, e.g. special flange/electronics/connections, etc.)

МНК5	E1: EPL V1 E2: EPL V2	A1	В	12	13	В	15	0	PRM
Absolute multi-turn encoder	Powerlink version	Version	Code: Binary	Number of revolutions: 2 ¹² (4,096)	Resolution in the revolution: 2 ¹³ (8,192)	Standard hollow shaft	Shaft diameter: 15 mm	Without mechanical option	M12 connector

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