

DSK5HKB MODELS

FUNCTIONAL SAFETY SIL3/PLE

This Quick Installation Guide is a summary of Chapter 4 "Installation and Start Up" from the "Safety User Manual". It is used as an aid during mounting to ensure that the Sensata | BEI Sensors safety encoders are correctly incorporated into safety system loops. More detailed information is available in the Safety User Manual on request. Customer documentation (Encoder datasheet, Safety EC-Type certificate, etc.) is available for customer download on Sensata website.



SAFETY INSTALLATION REQUIREMENTS

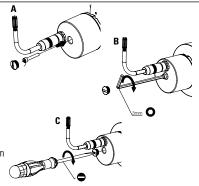
A WARNING / CAUTIONS

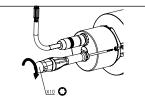
- The safety function requires that the four safety signals (A, A/ and B. B/ in digital or S, S/ and C, C/ in sine versions) are always connected to the safe PLC and used in the safety loop.
- Channel 0 (Z, Z/) is not part of the safety function. If Z, Z/ are not used they must be terminated through 3kOhm pull-down resistors connected to 0V.
- Good installation practice must be followed, including, but not limited to: tightening screws to proper torque, install all cover plugs correctly and never connect the encoder to power mains (115 VAC, 220 VAC)
- \bullet The safety system must be compliant with the following documents:
- Safety Loop Prerequisites (table to the right)
- Specifications in the Safety User Manual
- If external damage is detected on the box, inspect encoder carefully before mounting (connector, shaft, stator coupling...). Damage due to transport may lead to dangerous fault. In case of doubt, unit must be replaced.



MECHANICAL MOUNTING PROCEDURE

- Check the driving shaft runout and tolerance: diameter X H7. Clean the shafts interfaces (avoid particles and burrs).
- 2. Plug the encoder and driving shafts together.
- A. For a safe mounting secure the CHc M4x25mm screw with threadlocker Loctite 243 or equivalent.
- B. Tighten the M4 shaft screw with recommended torque: 3.5 N.m +/-10%.
- C. Tighten the axial sealing plug for insuring the IP protection with recommended torque:
- Slotted head (for axial covers): 3 N.m +/-10%
- Hex 8mm head (for radial covers): 4
 N.m +/-10%
- 4. Fasten the encoder on the frame
- For a safe mounting secure the screws with threadlocker Loctite 243 or equivalent.
- Check the position of the stator coupling. Avoid compressing or extending it to insure a minimal load on the bearing block.
- Tighten the 2 central or 4 shifted M3 screws at 1.8 N.m +/-10% with the ribbed lock washers.





External Safety Loop Prerequisites								
Electrical Encoder Version	Positive lock	Cable break detection	Safe supply voltage with monitoring	Vector length monitoring	Speed comparison	Zero crossing detection	Inverse signal monitoring	Exclusive bit check
2WT	Х	Х	Y ⁽¹⁾	Υ	Υ	Υ		
5WT	Х	Х		Υ	Υ	Υ		
2G2	Х	Х	Υ		Υ		Υ	Y ⁽¹⁾
5G5	Х	Х			Υ		Υ	Y ⁽¹⁾
5G2	Х	Х			Υ		Υ	Y ⁽¹⁾

- X: Prerequisite for all safety levels
- Y: Additional prerequisite for SIL3/PLe
- (1) Not required for SIL3/PLe for Speed without Direction

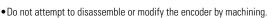


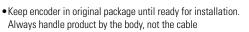
GENERAL MECHANICAL PRECAUTIONS

- Never hard couple both the body and the shaft of an encoder.
 Flexible couplings or other flexible mountings ensure long bearing life
- Avoid installing with the shaft upright as water can pool around the shaft and may eventually work its way into a sealed area
- It is good practice to use lockwashers and thread locker when mounting an encoder. Use the manufacturer's recommended torque for screws to ensure good mechanical and electrical function.
- Inspect connectors for damaged O-rings, threads or bent connector pins. Replace connector if necessary.



- Install so that the cable leads down and away from the encoder body. If the cable runs up it is susceptible to damage
- Do not subject the encoder to excessive shock (hammering or dropping).















ENCODER EXTRACTION PROCEDURE

1-Remove the cover plug

2- Unscrew slightly the CHc M4x25mm shaft screw (1 to 2 turns only)

3-Unscrew the anti-rotation device

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3-Enemove the CHc M10 extraction screw into encoder shaft. Apply progressive torque until encoder releases from driving shaft



GENERAL ELECTRICAL PRECAUTIONS

Cable	Follow good cable installation practices, including: Protecting cable from cuts or abrasion Follow recommend bend radius Provide a service loop from cable to mounting clamp to avoid damage due to snagging cable Avoid coiling up excess cable — trim to proper length for the installation
Connection	 Never connect data lines to each other or to a potential Refer to WARNINGS/CAUTIONS regarding handling of the 0 (Z and Z/) signals. Do not use the same cable for high power drive (motor drive, VFD) and encoder. Keep encoder signals separate from potential electrically interfering signals and follow proper shielding and grounding procedures. Metal connectors should have 360° shielding contact Connect each data line with its logical pair. i.e. A with A/, B with B/ and Z with Z/ in a differential receiver.
Grounding	Cable shield and encoder body should be connected at the same potential Do not leave the ground plane unconnected. Connect the cable shield ground to the control cabinet ground if available. Otherwise to 0V. Always ground the encoder housing to prevent electrostatic discharging through the mounting shaft.

ELECTRICAL MOUNTING PROCEDURE

- Verify that you have the correct power supply and that it is switched off prior to starting installation.
- Ensure that you have the correct wiring connections identified. Either through a sticker on the encoder or an installation manual.
- Make sure the cable run is in accordance with the tables shown in the installation guide.
- Power to the encoder and to the controller should be switched on (or off) simultaneously to ensure proper power up during initialization.

0	Cable Requirements				
Supply	Output	Length			
5VDC	2WTN	100 m			
	2G29	100 m ⁽¹⁾			
11-30 VDC	5WTN	100 m			
	5G29	100 m			
	5G59	100 m ⁽²⁾			

(1) Cable > 20 m use "GP" with voltage sensing power supply.
(2) Frequency restrictions — check "Safety User Manual"

Allowable Bend Radius				
Cable	Static	Dynamic		
G3-U3	30 mm	N/R		
GC	50 mm	150 mm		
TE	60 mm	60 mm		
GP	30 mm	90 mm		

Recommended Wire Cross Section			
Power	> 0.22 mm ²		
Data Signal	< 0.22 mm ²		

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