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CANopen ABSOLUTE SINGLE TURN ENCODERS, CHU9 RANGE

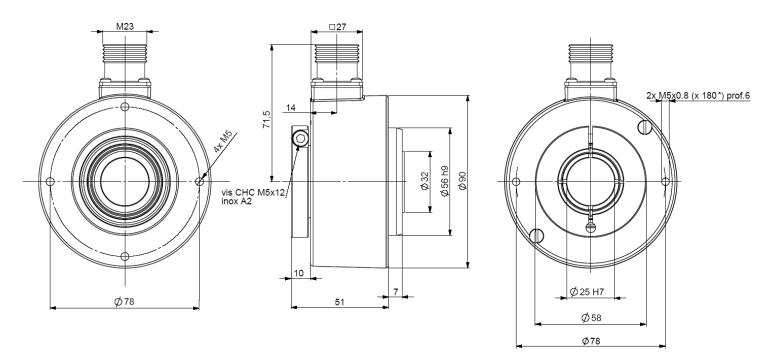
CHU9, the new generation of CANopen absolute single turn encoders :

- Through hollow shaft version Ø30mm, reduction hubs available,
- 90mm encoder, extra-flat,
- Robustness and excellent resistance to shocks / vibrations,
- High protection level IP65,
- High performances in temperature -20°C to 80°,
- Universal power supply from 5 to 30 Vdc,
- High resolutions up to 8192 points per turn (213).





CHU9_25 connection BCR (radial M23), with reduction hub 9418/I25 (25mm) mounted on the shaft



MECHANICAL CHARACTERISTICS

Material	Cover : zinc alloy	Vibrations (EN60068.2.6)	≤ 200m.s ⁻² (10 1 000Hz)	
Stainless steel option	Body : aluminium	EMC	EN 61000-6-4, EN 61000-6-2	
Shaft	Inox	Isolation	500V (1min)	
Bearings	6807 serie		0,700 kg	g zinc alloy cover, alu body
	Axial: 50 N	Encoder weight (approx.)	1,00 kg zinc alloy cover, stainless stee	
Maximal loads	Radial : 80 N		1,20 kg stainless steel cover and body	
Shaft inertia	≤ 55.10 ⁻⁶ kg.m ²	Operating temperature	- 20 + 80°C (encoder T°)	
Torque	≤ 25.10 ⁻³ N.m	Storage temperature	- 40 + 80°C	
Permissible max. speed	6 000 min ⁻¹	Protection(EN 60529)	IP 65	
Continuous max. speed	3 600 min ⁻¹	Torque (ring screw)	nominal: 3N.m, break: 4N.m	
Shaft seal	Viton	Theoretical mechanical lifetime 10° turns (F _{axial} / F _{radial})		
Shocks (EN60068.2.27)	≤ 500 m.s ⁻² (during 6 ms)	25 N / 40 N : 140 50 N /		50 N / 80 N : 17

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ELECTRICAL CHARACTERISTICS

Power supply	5 - 30Vdc
Introduction	< 1 s
Consumption (without load)	< 50mA (at 24Vdc)

Programmable parameters

Resolution: defines the resolution per revolution (0 to 8 192),

Transmission speed: programmable from 10kBaud (1000m) to 1 Mbaud (40 m); value per default: 20 Kbaud,

Address: define the software address of the encoder on the bus (1 to 127, value by default: id = 1),

Direction: define the direction of count of the encoder,

RAX: defines the value of its preset position (non turning shaft),

CAM: Low and High Limits.

Communication modes

3 modes are available to interrogate the encoder:

POLLING mode: (Response to a RTR message): The position value is only given upon request (SDO mode),

CYCLIC mode: the encoder transmits its position in an asynchronous manner. The frequency of the transmission is defined by the programmable cyclical timer register from 0 to 65 535 ms,

SYNCHRO mode: the encoder transmits its position on a synchronous demand by the master.

CANOPEN CONNECTION

1	2	3	4	5	6	7	8, 9, 11	10	12
Reserved	CAN LOW	CAN GND	Reserved	Reserved	Reserved	CAN HIGH	Reserved	0V	+ 5/30Vdc

Pinout 3 (CAN GND) and 10 (0V) are connected together (intern the encoder).

Nota: Refer to the bus standards for the maximal derivation length.

ORDERING CODE (Special versions upon request, for ex. special flanges/electronics/connections...)

	Shaft Ø	Power supply	Output stage	Code	Resolution	Connection	Connection orientation
CHU9	30 :	P :	BB:	B:	13 :	BC:	R :
	30mm Reduction hubs available	5 to 30Vdc	CANopen	Binary	8192 ppoints per revolution (2 ¹³)	M23 12 pinouts clockwise	radial
CHU9 _	30 //	Р	ВВ	В //	13 //	ВС	R

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